

Gevrey regularity for a system coupling the Navier-Stokes equations with a beam

Mehdi Badra

joint work with Takéo Takahashi

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Plan

- 1 Presentation of the problem
- 2 Sketch of the proof
- 3 A control issue

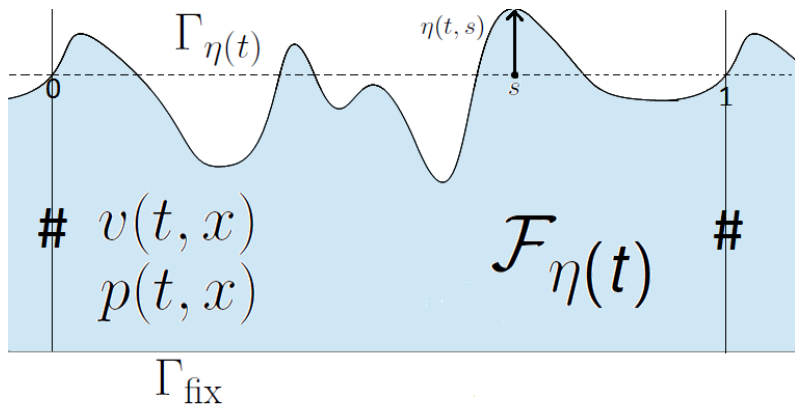
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2D fluid-structure interaction system



Fluid equations

- Navier-Stokes equations for the velocity of the fluid :

$$\left\{ \begin{array}{l} \partial_t \mathbf{v} + (\mathbf{v} \cdot \nabla) \mathbf{v} - \operatorname{div} \mathbb{T}(\mathbf{v}, p) = 0 \quad \text{in } \mathcal{F}_{\eta(t)}, t > 0 \\ \operatorname{div} \mathbf{v} = 0 \quad \text{in } \mathcal{F}_{\eta(t)}, t > 0 \\ \mathbf{v}, p \text{ 1-periodic in the variable } x_1 \end{array} \right.$$

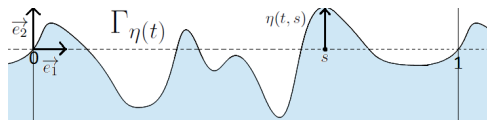
where $\mathbb{T}(\mathbf{v}, p) \stackrel{\text{def}}{=} 2\nu D(\mathbf{v}) - p \operatorname{Id}$, $D(\mathbf{v}) \stackrel{\text{def}}{=} \frac{1}{2} ((\nabla \mathbf{v}) + {}^t(\nabla \mathbf{v}))$

- Condition on the fixed part of the boundary :

$$\mathbf{v} = 0 \quad \text{on } \Gamma_{\text{fix}}, t > 0.$$

Structure equation

- Structure interface : $\Gamma_{\eta(t)} = \{(s, \eta(t, s)) \mid s \in (0, 1)\}, t > 0$.



- Interface condition :

$$\mathbf{v}(t, s, \eta(t, s)) = (\partial_t \eta)(t, s) \vec{e}_2, \quad s \in (0, 1), t > 0$$

- Vertical force exerted by the fluid on the structure :

$$\tilde{\mathbf{F}}_{\text{fluid} \rightarrow \text{str}}(\mathbf{v}, \rho)(t, s) = -\sqrt{1 + |\partial_s \eta(t, s)|^2} [\mathbb{T}(\mathbf{v}, \rho) \boldsymbol{\eta}](s, \eta(t, s)) \cdot \vec{e}_2$$

- Beam equation for the deformation ($\alpha > 0$ rigidity ; $\beta \geq 0$ stretching) :

$$\partial_{tt} \eta + \alpha \partial_{ssss} \eta - \beta \partial_{ss} \eta = \tilde{\mathbf{F}}_{\text{fluid} \rightarrow \text{str}}(\mathbf{v}, \rho), \quad s \in (0, 1), t > 0,$$

η 1-periodic in the variable s .

Structure equation

- Compatibility condition :

$$0 = \int_{\mathcal{F}_{\eta(t)}} \operatorname{div}(\mathbf{v}) dx = \int_{\partial\mathcal{F}_{\eta(t)}} \mathbf{v} \cdot \mathbf{n} d\gamma = \int_0^1 \partial_t \eta(t, s) ds = \frac{d}{dt} \int_0^1 \eta(t, s) ds$$
$$\rightsquigarrow \int_0^1 \eta(t, s) ds = 0, t > 0.$$

- Then p is not determined up to a constant and satisfies

$$\int_0^1 \left(p(t, s, \eta(t, s)) - 2\nu \left\{ (1 + |\partial_s \eta|^2)^{1/2} [D(\mathbf{v})\boldsymbol{\eta}](t, s, 1 + \eta(t, s)) \cdot \mathbf{e}_2 \right\} \right) ds = 0$$

- To hide this constraint we introduce :

$$M : L_{\#}^2(0, 1) \rightarrow \left\{ f \in L_{\#}^2(0, 1) \mid \int_0^1 f ds = 0 \right\}, F_{\text{fluid} \rightarrow \text{str}}(\mathbf{v}, p) = M\tilde{F}_{\text{fluid} \rightarrow \text{str}}(\mathbf{v}, p)$$

$$\rightsquigarrow \partial_{tt}\eta + \alpha \partial_{ssss}\eta - \beta \partial_{ss}\eta = F_{\text{fluid} \rightarrow \text{str}}(\mathbf{v}, p), \mathbf{s} \in (0, 1), t > 0.$$

2D fluid-structure interaction system

$$\left\{ \begin{array}{l} \partial_t \mathbf{v} + (\mathbf{v} \cdot \nabla) \mathbf{v} - \operatorname{div} \mathbb{T}(\mathbf{v}, p) = 0 \quad \text{in } \mathcal{F}_{\eta(t)}, \quad t > 0 \\ \operatorname{div} \mathbf{v} = 0 \quad \text{in } \mathcal{F}_{\eta(t)}, \quad t > 0 \\ \mathbf{v} = \partial_t \eta \vec{\mathbf{e}}_2 \quad \text{on } \Gamma_{\eta(t)}, \quad t > 0 \\ \mathbf{v} = 0 \quad \text{on } \Gamma_{\text{fix}}, \quad t > 0 \\ \partial_{tt} \eta + \alpha \partial_{ssss} \eta - \beta \partial_{ss} \eta = F_{\text{fluid} \rightarrow \text{str}}(\mathbf{v}, p), \quad \mathbf{s} \in (0, 1), \quad t > 0, \\ \eta \text{ 1-periodic in the variable } \mathbf{s}, \quad \int_0^1 \eta ds = 0, \quad t > 0 \\ \eta(0) = \eta_1^0, \quad \partial_t \eta(0) = \eta_2^0, \quad \mathbf{v}(0, \mathbf{x}) = \mathbf{v}^0(\mathbf{x}) \quad \mathbf{x} \in \mathcal{F}_{\eta_1^0}. \end{array} \right.$$

with

$$F_{\text{fluid} \rightarrow \text{str}}(\mathbf{v}, p)(t, \mathbf{s}) = -M \sqrt{1 + |\partial_s \eta(t, \mathbf{s})|^2} [\mathbb{T}(\mathbf{v}, p) \mathbf{n}](\mathbf{s}, \eta(t, \mathbf{s})) \cdot \vec{\mathbf{e}}_2$$

Definition of strong solutions and assumptions

Strong solution (v, η, p) on $[0, T]$:

$$v \in L^2(0, T; \mathbf{H}^2(\mathcal{F}_\eta)) \cap C_b([0, T]; \mathbf{H}^1(\mathcal{F}_\eta)) \cap H^1(0, T; \mathbf{L}^2(\mathcal{F}_\eta)),$$

$$p \in L^2(0, T; H^1(\mathcal{F}_\eta))$$

$$\eta \in L^2(0, T; H_{\#}^{7/2}(0, 1)) \cap C_b([0, T]; H_{\#}^{5/2}(0, 1)) \cap H^1(0, T; H_{\#}^{3/2}(0, 1)),$$

$$\partial_t \eta \in L^2(0, T; H_{\#}^{3/2}(0, 1)) \cap C_b([0, T]; H_{\#}^{1/2}(0, 1)) \cap H^1(0, T; (H_{\#}^{1/2}(0, 1))'),$$

Assumptions on the initial conditions (AIC) :

$$\eta_1^0 \in H_{\#}^{3+\varepsilon}(0, 1), \quad \eta_2^0 \in H_{\#}^{1+\varepsilon}(0, 1), \quad \eta^0 > -1,$$

$$\int_0^1 \eta_1^0 ds = \int_0^1 \eta_2^0 ds = 0$$

$$v^0 \in \mathbf{H}^1(\mathcal{F}_{\eta_1^0}) \quad \text{and} \quad v^0 \text{ e}_1 - \text{periodic},$$

$$\operatorname{div} v^0 = 0 \text{ in } \mathcal{F}_{\eta_1^0},$$

$$v^0(s, 1 + \eta_1^0(s)) = \eta_2^0(s) \vec{e}_2 \quad s \in (0, 1),$$

$$v^0 = 0 \quad \text{on } \Gamma_{\text{fix}}.$$

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$$p \in L^2(0, T; H^1(\mathcal{F}_\eta))$$

$$\eta \in L^2(0, T; H_{\#}^{7/2}(0, 1)) \cap C_b([0, T]; H_{\#}^{5/2}(0, 1)) \cap H^1(0, T; H_{\#}^{3/2}(0, 1)),$$

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Local existence theorem

Theorem

Assume that v^0, η_1^0, η_2^0 satisfy (AIC). Then there exists $C_0 > 0$ such that if

$$\| [v^0, \eta_1^0, \eta_2^0] \|_{\mathbf{H}^1(\mathcal{F}(\eta_1^0)) \times H_{\#}^{3+\varepsilon}(0,1) \times H_{\#}^{1+\varepsilon}(0,1)} \leq C_0,$$

then there exists a strong solution (η, v, p) on $[0, +\infty)$ such that

$$\eta(t, \cdot) > -1 \quad t \in [0, \infty).$$

Theorem

Assume that v^0, η_1^0, η_2^0 satisfy (AIC). Then there exists $T > 0$ and $C_0 > 0$ such that if

$$\|\eta_1^0\|_{H^2(0,1)} \leq C_0$$

then there exists a strong solution (η, v, p) on $[0, T]$ such that

$$\eta(t, \cdot) > -1 \quad t \in [0, T].$$

↪ B, Takahashi (SIMA 2019).

Local existence theorem

Theorem (B, Takahashi (2019))

Assume that v^0, η_1^0, η_2^0 satisfy (AIC). Assume also that

$$\eta_1^0 \in W^{7,\infty}(0, 1).$$

Then there exists $T > 0$ and a strong solution (η, v, p) on $[0, T]$ such that

$$\eta(t, \cdot) > -1 \quad t \in [0, T].$$

↔ B, Takahashi (just finalized!).

Open questions

- Initial deformation η_1^0 less regular ($\eta_1^0 \notin W^{7,\infty}(0,1)$) ?
- Initial regularity is not transported :
 - \rightsquigarrow Blow up or contact if $T_{\max} < +\infty$?
 - \rightsquigarrow Uniqueness ?
- Global existence ?
- Control issues ?

The damped case

$$\partial_{tt}\eta - \underbrace{\delta \partial_{sst}\eta}_{\text{damping}} + \alpha \partial_{ssss}\eta - \beta \partial_{ss}\eta = F_{\text{fluid} \rightarrow \text{str}}(v, p). \quad (\delta > 0)$$

Model.

- Quarteroni, Tuveri, Veneziani (2000) (cardiovascular model).

Well-posedness.

- Beirao da Veiga (2004), Chambolle-Desjardin-Esteban-Grandmont (2005), Lequeurre (2011, 2013), Grandmont- Hillairet (2016), Grandmont-Hillairet-Lequeurre (2019).

Stabilization.

- Raymond (2010), B-Takahashi (2017), Casanova (2018).

The non damped case :

$$\partial_{tt}\eta + \alpha\partial_{ssss}\eta - \beta\partial_{ss}\eta = F_{\text{fluid}\rightarrow\text{str}}(\mathbf{v}, p).$$

Well-posedness.

- [Grandmont \(2008\)](#) (Weak solutions),
- [Grandmont- Hillairet-Lequeurre \(2019\)](#) (Wave equation : $\alpha = 0, \beta > 0$).

Damped case v.s. non damped case

- Damped beam equation : $\alpha > 0$, $\beta \geq 0$ and $\delta > 0$,

$$\partial_{tt}\eta \underbrace{- \delta \partial_{sst}\eta}_{\text{damping}} + \alpha \partial_{ssss}\eta - \beta \partial_{ss}\eta = F_{\text{fluid} \rightarrow \text{str}}(\mathbf{v}, \rho).$$

Parabolic / Parabolic coupling \implies Parabolic

- Non damped beam equation $\alpha > 0$, $\beta \geq 0$,

$$\partial_{tt}\eta + \alpha \partial_{ssss}\eta - \beta \partial_{ss}\eta = F_{\text{fluid} \rightarrow \text{str}}(\mathbf{v}, \rho).$$

Parabolic / Hyperbolic coupling \implies ????

Damped case v.s. non damped case

- Damped beam equation : $\alpha > 0$, $\beta \geq 0$ and $\delta > 0$,

$$\partial_{tt}\eta - \underbrace{\delta \partial_{sst}\eta}_{\text{damping}} + \alpha \partial_{ssss}\eta - \beta \partial_{ss}\eta = F_{\text{fluid} \rightarrow \text{str}}(v, p).$$

Parabolic / Parabolic coupling \implies Parabolic

- Non damped beam equation $\alpha > 0$, $\beta \geq 0$,

$$\partial_{tt}\eta - \underbrace{F_{\text{fluid} \rightarrow \text{str}}(v, p)}_{\text{damping}} + \alpha \partial_{ssss}\eta - \beta \partial_{ss}\eta = 0.$$

**Parabolic / Hyperbolic coupling \implies Quasi-parabolic
(Gevrey semigroup)**

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$$\alpha > 0, \quad \beta \geq 0$$

$\delta > 0$ (damped case) or $\delta = 0$ (non damped case).

Structure equation

- State space and operators :

$$\mathcal{H}_S \stackrel{\text{def}}{=} \left\{ f \in L^2_{\#}(0, 1) \mid \int_0^1 f ds = 0 \right\}$$

$$A_1 \eta = \alpha \partial_{ssss} \eta - \beta \partial_{ss} \eta \quad \mathcal{D}(A_1) = H^4_{\#}(0, 1) \cap \mathcal{H}_S,$$

$$\begin{cases} A_2 \eta = -\delta \partial_{ss} \eta, & \mathcal{D}(A_2) = H^2_{\#}(0, 1) \cap \mathcal{H}_S = \mathcal{D}(A_1^{1/2}) & \text{if } \delta > 0, \\ A_2 \eta = 0 & & \text{if } \delta = 0, \end{cases}$$

- Structure equation :

$$\partial_{tt} \eta + A_2 \partial_t \eta + A_1 \eta = F_{\text{fluid} \rightarrow \text{str}}(v, p), \quad t > 0.$$

Structure equation

- Boundary operator :

$$\Lambda_\eta : \mathcal{H}_S \rightarrow \mathbf{L}^2(\partial\mathcal{F}_\eta), \quad (\Lambda_\eta \xi)(t, y_1, y_2) = \begin{cases} \xi(t, y_1) \vec{e}_2 & \text{if } (y_1, y_2) \in \Gamma_\eta, \\ 0 & \text{if } (y_1, y_2) \in \Gamma_{\text{fix}}. \end{cases}$$

- Boundary conditions and force exerted by the fluid :

$$\mathbf{v} = \mathbf{0} \text{ on } \Gamma_{\text{fix}} \quad \text{and} \quad \mathbf{v}(t, s, \eta(t, s)) = (\partial_t \eta)(t, s) \vec{e}_2, \quad s \in (0, 1), t > 0$$

$$\rightsquigarrow \mathbf{v} = \Lambda_\eta \partial_t \eta \text{ on } \partial\mathcal{F}_{\eta(t)}, t > 0$$

$$F_{\text{fluid} \rightarrow \text{str}}(\mathbf{v}, p)(t, s) = -M \sqrt{1 + |\partial_s \eta(t, s)|^2} [\mathbb{T}(\mathbf{v}, p) \mathbf{n}](s, \eta(t, s)) \cdot \vec{e}_2$$

$$\rightsquigarrow F_{\text{fluid} \rightarrow \text{str}}(\mathbf{v}, p) = -\Lambda_\eta^* \mathbb{T}(\mathbf{v}, p) \mathbf{n}$$

- Structure equation :

$$\partial_{tt} \eta + A_2 \partial_t \eta + A_1 \eta = -\Lambda_\eta^* \mathbb{T}(\mathbf{v}, p) \mathbf{n}, \quad t > 0.$$

2D fluid-structure interaction system

$$\left\{ \begin{array}{l} \partial_t \mathbf{v} + (\mathbf{v} \cdot \nabla) \mathbf{v} - \operatorname{div} \mathbb{T}(\mathbf{v}, \mathbf{p}) = 0 \quad \text{in } \mathcal{F}_{\eta(t)}, \quad t > 0 \\ \operatorname{div} \mathbf{v} = 0 \quad \text{in } \mathcal{F}_{\eta(t)}, \quad t > 0 \\ \mathbf{v} = \Lambda_{\eta} \partial_t \eta \quad \text{on } \partial \mathcal{F}_{\eta(t)}, \quad t > 0 \\ \partial_{tt} \eta + \mathbf{A}_2 \partial_t \eta + \mathbf{A}_1 \eta = -\Lambda_{\eta}^* \mathbb{T}(\mathbf{v}, \mathbf{p}) \mathbf{n}, \quad t > 0, \\ \eta(0) = \eta_1^0, \quad \partial_t \eta(0) = \eta_2^0, \quad \mathbf{v}(0, \mathbf{x}) = \mathbf{v}^0(\mathbf{x}) \quad \mathbf{x} \in \mathcal{F}_{\eta_1^0}. \end{array} \right.$$

Change of variables

$$X : \mathcal{F}_{\eta_1^0} \rightarrow \mathcal{F}_{\eta(t)}, \quad X(t, y_1, y_2) \stackrel{\text{def}}{=} \left(y_1, \frac{y_2}{1 + \zeta(t, y_1)} \right),$$

$$\text{with } \zeta(t, y_1) \stackrel{\text{def}}{=} \frac{\eta(t, y_1) - \eta_1^0(y_1)}{1 + \eta_1^0(y_1)}$$

New velocity and pressure :

$$w(t, y) \stackrel{\text{def}}{=} \text{Cof}(\nabla X(t, y))^* v(t, X(t, y)) \quad \text{and} \quad q(t, y) \stackrel{\text{def}}{=} p(t, X(t, y)).$$

Remark : The above definition with $\eta_1^0 = 0$ corresponds to a flat reference geometry for the structure (case treated in [B, Takahashi \(SIMA 2019\)](#)).

System rewritten in a fixed domain

$$\left\{ \begin{array}{l} \partial_t \mathbf{w} - \operatorname{div} \mathbb{T}(\mathbf{w}, \mathbf{q}) = \mathbf{f}(\zeta, \mathbf{w}, \mathbf{q}) \quad \text{in } \mathcal{F}_{\eta_1^0}, \quad t > 0 \\ \operatorname{div} \mathbf{w} = 0 \quad \text{in } \mathcal{F}_{\eta_1^0}, \quad t > 0 \\ \mathbf{v} = \Lambda_{\eta_1^0} \partial_t \eta \quad \text{on } \partial \mathcal{F}_{\eta_1^0}, \quad t > 0 \\ \partial_{tt} \eta + \mathbf{A}_2 \partial_t \eta + \mathbf{A}_1 \eta = -\Lambda_{\eta_1^0}^* \mathbb{T}(\mathbf{w}, \mathbf{q}) \mathbf{n} + \mathbf{g}(\zeta, \mathbf{w}, \mathbf{q}), \quad t > 0, \\ \eta(0) = \eta_1^0, \quad \partial_t \eta(0) = \eta_2^0, \quad \mathbf{w}(0, \mathbf{x}) = \mathbf{w}^0(\mathbf{x}) \quad \mathbf{x} \in \mathcal{F}_{\eta_1^0}. \end{array} \right.$$

$$\rightsquigarrow Y' = AY + F, \quad Y(0) = Y_0 \in H$$

System rewritten in a fixed domain

$$\left\{ \begin{array}{l} \partial_t \mathbf{w} - \operatorname{div} \mathbb{T}(\mathbf{w}, q) = \mathbf{f} \quad \text{in } \mathcal{F}_{\eta_1^0}, \quad t > 0 \\ \operatorname{div} \mathbf{w} = 0 \quad \text{in } \mathcal{F}_{\eta_1^0}, \quad t > 0 \\ \mathbf{v} = \Lambda_{\eta_1^0} \partial_t \eta \quad \text{on } \mathcal{F}_{\eta_1^0}, \quad t > 0 \\ \partial_{tt} \eta + \mathbf{A}_2 \partial_t \eta + \mathbf{A}_1 \eta = -\Lambda_{\eta_1^0}^* \mathbb{T}(\mathbf{w}, q) \mathbf{n} + \mathbf{g}, \quad t > 0, \\ \eta(0) = \eta_1^0, \quad \partial_t \eta(0) = \eta_2^0, \quad \mathbf{w}(0, \mathbf{x}) = \mathbf{w}^0(\mathbf{x}) \quad \mathbf{x} \in \mathcal{F}_{\eta_1^0}. \end{array} \right.$$

$$\rightsquigarrow Y' = AY + F, \quad Y(0) = Y_0 \in H$$

System rewritten in a fixed domain

With $\eta_1 = \eta$ and $\eta_2 = \partial_t \eta$ the system rewrites :

$$\left\{ \begin{array}{l} \partial_t w - \operatorname{div} \mathbb{T}(w, q) = f \quad \text{in } \mathcal{F}_{\eta_1^0}, t > 0 \\ \operatorname{div} w = 0 \quad \text{in } \mathcal{F}_{\eta_1^0}, t > 0 \\ v = \Lambda_{\eta_1^0} \eta_2 \quad \text{on } \partial \mathcal{F}_{\eta_1^0}, t > 0 \\ \partial_t \eta_1 = \eta_2, t > 0, \\ \partial_t \eta_2 + A_2 \eta_2 + A_1 \eta_1 = -\Lambda_{\eta_1^0}^* \mathbb{T}(w, q) n + g, t > 0, \\ \eta_1(0) = \eta_1^0, \quad \eta_2(0) = \eta_2^0, \quad w(0, x) = w^0(x) \quad x \in \mathcal{F}_{\eta_1^0}. \end{array} \right.$$

$$\rightsquigarrow Y' = AY + F, \quad Y(0) = Y_0 \in H$$

System rewritten in a fixed domain

$$\left\{ \begin{array}{l} \partial_t \mathbf{w} - \operatorname{div} \mathbb{T}(\mathbf{w}, \mathbf{q}) = \mathbf{f} \quad \text{in } \mathcal{F}_{\eta_1^0}, \quad t > 0 \\ \operatorname{div} \mathbf{w} = 0 \quad \text{in } \mathcal{F}_{\eta_1^0}, \quad t > 0 \\ \mathbf{v} = \Lambda_{\eta_1^0} \eta_2 \quad \text{on } \partial \mathcal{F}_{\eta_1^0}, \quad t > 0 \\ \partial_t \eta_1 = \eta_2, \quad t > 0, \\ \partial_t \eta_2 + \mathbf{A}_2 \eta_2 + \mathbf{A}_1 \eta_1 = -\Lambda_{\eta_1^0}^* \mathbb{T}(\mathbf{w}, \mathbf{q}) \mathbf{n} + \mathbf{g}, \quad t > 0, \\ \eta_1(0) = \eta_1^0, \quad \eta_2(0) = \eta_2^0, \quad \mathbf{w}(0, \mathbf{x}) = \mathbf{w}^0(\mathbf{x}) \quad \mathbf{x} \in \mathcal{F}_{\eta_1^0}. \end{array} \right.$$

$$\rightsquigarrow Y' = AY + F, \quad Y(0) = Y_0 \in H$$

Functional framework

- State space

$$H \stackrel{\text{def}}{=} \left\{ \begin{bmatrix} w \\ \eta_1 \\ \eta_2 \end{bmatrix} \in \mathbf{L}^2(\mathcal{F}_{\eta_1^0}) \times \mathcal{D}(\mathbf{A}_1^{1/2}) \times \mathcal{H}_S \left| \begin{array}{l} w \cdot n = \Lambda_{\eta_1^0} \eta_2 \cdot n \text{ on } \partial \mathcal{F}_{\eta_1^0}, \\ \operatorname{div} w = 0 \text{ in } \mathcal{F}_{\eta_1^0}, \end{array} \right. \right\}$$

- Orthogonal projection operator

$$P_H : \mathbf{L}^2(\mathcal{F}_{\eta_1^0}) \times \mathcal{D}(\mathbf{A}_1^{1/2}) \times \mathcal{H}_S \rightarrow H$$

- Linear operator

$$\mathcal{D}(A) \stackrel{\text{def}}{=} \left\{ \begin{bmatrix} w \\ \eta_1 \\ \eta_2 \end{bmatrix} \in \mathbf{H}^2(\mathcal{F}_{\eta_1^0}) \times \mathcal{D}(\mathbf{A}_1) \times \mathcal{D}(\mathbf{A}_1^{1/2}) \left| \begin{array}{l} w = \Lambda_{\eta_1^0} \eta_2 \text{ on } \partial \mathcal{F}_{\eta_1^0}, \\ \operatorname{div} w = 0 \text{ in } \mathcal{F}_{\eta_1^0}, \end{array} \right. \right\}$$

$$A \begin{bmatrix} w \\ \eta_1 \\ \eta_2 \end{bmatrix} \stackrel{\text{def}}{=} P_H \begin{bmatrix} \nu \Delta w \\ \eta_2 \\ -A_2 \eta_2 - A_1 \eta_1 - \Lambda_{\eta_1^0}^* [D(w)n] \end{bmatrix}$$

A generates a stable strongly continuous semigroup $(e^{tA})_{t>0}$ on H

Linearized system

Moreover, with

$$Y = \begin{bmatrix} w \\ \eta_1 \\ \eta_2 \end{bmatrix}, \quad Y_0 = \begin{bmatrix} w_0 \\ \eta_1^0 \\ \eta_2^0 \end{bmatrix} \quad \text{and} \quad F = \begin{bmatrix} f \\ 0 \\ g \end{bmatrix}$$

the system rewrites

$$Y' = AY + F, \quad Y(0) = Y_0.$$

But to use a fixed point argument we need sufficiently strong regularity estimates for the above nonhomogeneous equation...

The damped case :

$$A_2 = -\delta \partial_{ss}, \delta > 0$$

The damped case $A_2 = -\delta \partial_{SS}$, $\delta > 0$

Key point :

$$t \in (0, +\infty) \mapsto e^{tA} \in H \text{ is analytic,}$$

or equivalently,

there exist $C > 0$, $\alpha > 0$ such that :

$$\forall \lambda \in \mathbb{C}^+, |\lambda| > \alpha, \quad \|(\lambda - A)^{-1}\|_{\mathcal{L}(H)} \leq \frac{C}{|\lambda|}.$$

It implies maximal regularity result :

$$\begin{aligned} \|Y'\|_{L^2(0,T;H)} + \|AY\|_{L^2(0,T;H)} + \|(-A)^{1/2}Y\|_{C([0,T];H)} \\ \leq C(\|F\|_{L^2(0,T;H)} + \|(-A)^{1/2}Y_0\|_H), \end{aligned}$$

which is sufficient to conclude with a fixed point argument...

The damped case $A_2 = -\delta \partial_{SS}$, $\delta > 0$

$$(\lambda - A)[v, \eta_1, \eta_2] = [f, g, h]$$

$$\Downarrow$$

$$\left\{ \begin{array}{l} \lambda v - \operatorname{div} \mathbb{T}(v, p) = f \quad \text{in } \mathcal{F}_{\eta_1^0}, \\ \operatorname{div} v = 0 \quad \text{in } \mathcal{F}_{\eta_1^0}, \\ v = \Lambda_{\eta_1^0} \eta_2 \quad \text{on } \partial \mathcal{F}_{\eta_1^0}, \\ \lambda \eta_1 - \eta_2 = g \\ \lambda \eta_2 + A_2 \eta_2 + \Lambda_{\eta_1^0}^* \mathbb{T}(v, p)n + A_1 \eta_1 = h. \end{array} \right.$$

The resolvent estimate to prove is

$$|\lambda| \| [v, \eta_1, \eta_2] \|_H \leq C \| [f, g, h] \|_H.$$

The damped case $A_2 = -\delta \partial_{SS}$, $\delta > 0$

With

$$f = 0 \quad g = 0$$

and

$$L(\lambda)\eta_1 \stackrel{\text{def}}{=} \Lambda_{\eta_1^0}^* \mathbb{T}(v_{\eta_1}, p_{\eta_1})n \text{ where } \begin{cases} \lambda v_{\eta_1} - \operatorname{div} \mathbb{T}(v_{\eta_1}, p_{\eta_1}) = 0 & \text{in } \mathcal{F}_{\eta_1^0}, \\ \operatorname{div} v_{\eta_1} = 0 & \text{in } \mathcal{F}_{\eta_1^0}, \\ v_{\eta_1} = \Lambda_{\eta_1^0} \eta_1 & \text{on } \partial \mathcal{F}_{\eta_1^0}. \end{cases}$$

The resolvent equation reduces to

$$\lambda^2 \eta_1 + \lambda A_2 \eta_1 + \lambda L(\lambda) \eta_1 + A_1 \eta_1 = h.$$

Moreover, the resolvent estimate to prove reduces to

$$|\lambda|^2 \|\eta_1\|_{\mathcal{H}_S} \leq C \|h\|_{\mathcal{H}_S}.$$

The damped case $A_2 = -\delta \partial_{SS}$, $\delta > 0$

Write

$$\lambda^2 \eta_1 + \lambda A_2 \eta_1 + A_1 \eta_1 = h - \lambda L(\lambda) \eta_1,$$

and use a perturbation argument thanks to :

[Chen Triggiani, 1989]

If A_2 satisfies $\rho_1 A_1^{1/2} \leq A_2 \leq \rho_2 A_1^{1/2}$, ($0 < \rho_1 < \rho_2 < +\infty$), then there exists $C > 0$ such that for all $\lambda \in \mathbb{C}^+$ the solution of

$$\lambda^2 \eta_1 + \lambda A_2 \eta_1 + A_1 \eta_1 = h,$$

satisfies

$$|\lambda|^2 \|\eta_1\|_{\mathcal{H}_S} + \|A_1 \eta_1\|_{\mathcal{H}_S} \leq C \|h\|_{\mathcal{H}_S}.$$

As a consequence, the semigroup associated to the the underlying beam equation is analytic.

Indeed, we have

$$\|\lambda L(\lambda) \eta_1\| \leq C |\lambda|^{-1/2+\epsilon} (|\lambda|^2 \|\eta_1\|_{\mathcal{H}_S} + \|A_1 \eta_1\|_{\mathcal{H}_S})$$

and we conclude with $|\lambda|$ large enough.

The non damped case :

$$A_2 = 0$$

The non damped case $A_2 = 0$

Key point :

There exist $C > 0, \alpha > 0$ such that :

$$\forall \lambda \in \mathbb{C}^+, \lambda > \alpha, \quad \|(\lambda - A)^{-1}\|_{\mathcal{L}(H)} \leq \frac{C}{|\lambda|^{1/2}}$$

which implies

for all $\gamma > 2, t \in (0, +\infty) \mapsto e^{tA} \in H$ is of Gevrey class γ

($t \in (0, +\infty) \mapsto e^{tA} \in H$ is of Gevrey class γ means that for all compact $K \subset (0, +\infty)$ there exist $C, R > 0$, such that $\forall t \in K, \left\| \frac{d^n e^{tA}}{dt^n} \right\|_H \leq CR^n (n!)^\gamma$.)

The above estimate implies the following regularity result :

$$\begin{aligned} \|Y'\|_{L^2(0,T;H)} + \|AY\|_{L^2(0,T;H)} + \|(-A)^{1/2}Y\|_{C([0,T];H)} \\ \leq C(\|(-A)^{1/2}F\|_{L^2(0,T;H)} + \|(-A)^{3/4+\varepsilon/2}Y_0\|_H). \end{aligned}$$

... and we conclude with a fixed point argument...

The non damped case $A_2 = 0$

$$(\lambda - A)[v, \eta_1, \eta_2] = [f, g, h]$$

$$\Updownarrow$$

$$\left\{ \begin{array}{l} \lambda v - \operatorname{div} \mathbb{T}(v, p) = f \quad \text{in } \mathcal{F}_{\eta_1^0}, \\ \operatorname{div} v = 0 \quad \text{in } \mathcal{F}_{\eta_1^0}, \\ v = \Lambda_{\eta_1^0} \eta_2 \quad \text{on } \partial \mathcal{F}_{\eta_1^0}, \\ \lambda \eta_1 - \eta_2 = g \\ \lambda \eta_2 + \Lambda_{\eta_1^0}^* \mathbb{T}(v, p)n + A_1 \eta_1 = h. \end{array} \right.$$

The resolvent estimate to prove is

$$|\lambda|^{1/2} \|[v, \eta_1, \eta_2]\|_H \leq C \|[f, g, h]\|_H.$$

The non damped case $A_2 = 0$

With

$$f = 0 \quad g = 0$$

and

$$L(\lambda)\eta_1 \stackrel{\text{def}}{=} \Lambda_{\eta_1^0}^* \mathbb{T}(v_{\eta_1}, p_{\eta_1})n \text{ where } \begin{cases} \lambda v_{\eta_1} - \operatorname{div} \mathbb{T}(v_{\eta_1}, p_{\eta_1}) = 0 & \text{in } \mathcal{F}_{\eta_1^0}, \\ \operatorname{div} v_{\eta_1} = 0 & \text{in } \mathcal{F}_{\eta_1^0}, \\ v_{\eta_1} = \Lambda_{\eta_1^0} \eta_1 & \text{on } \partial \mathcal{F}_{\eta_1^0}. \end{cases}$$

The resolvent equation reduces to

$$\lambda^2 \eta_1 + \lambda L(\lambda) \eta_1 + A_1 \eta_1 = h.$$

Moreover, the resolvent estimate to be proved reduces to

$$|\lambda|^{3/2} \|\eta_1\|_{\mathcal{H}_S} \leq C \|h\|_{\mathcal{H}_S}.$$

The non damped case $A_2 = 0$

From an integration by parts we first observe that

$$\langle L(\lambda)\eta_1, \eta_1 \rangle_{\mathcal{H}_S} = \lambda \underbrace{\int_{\mathcal{F}_{\eta_1^0}} |\mathbf{v}_{\eta_1}|^2 dy}_{\langle K(\lambda)\eta_1, \eta_1 \rangle_{\mathcal{H}_S}} + \underbrace{\int_{\mathcal{F}_{\eta_1^0}} |\nabla \mathbf{v}_{\eta_1}|^2 dy}_{\langle G(\lambda)\eta_1, \eta_1 \rangle_{\mathcal{H}_S}}.$$

$$\rightsquigarrow L(\lambda) = \lambda K(\lambda) + G(\lambda)$$

with $K(\lambda)$ and $G(\lambda)$ self-adjoint satisfying

$$0 < K(\lambda) \leq \rho_2 A_1^{-1/4} \quad \text{and} \quad \rho_1 A_1^{1/4} \leq G(\lambda) \leq \rho_2 \left(A_1^{1/4} + |\lambda| A_1^{-1/4} \right)$$

$$\rightsquigarrow \lambda^2(\eta_1 + K(\lambda)\eta_1) + \lambda G(\lambda)\eta_1 + A_1\eta_1 = h.$$

A (tricky) perturbation argument allows to replace $G(\lambda)$ by $A_1^{1/4}$ and consider

$$\lambda^2(\eta_1 +) + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1 = h.$$

The non damped case $A_2 = 0$

From an integration by parts we first observe that

$$\langle L(\lambda)\eta_1, \eta_1 \rangle_{\mathcal{H}_S} = \lambda \underbrace{\int_{\mathcal{F}_{\eta_1^0}} |v_{\eta_1}|^2 dy}_{\langle K(\lambda)\eta_1, \eta_1 \rangle_{\mathcal{H}_S}} + \underbrace{\int_{\mathcal{F}_{\eta_1^0}} |\nabla v_{\eta_1}|^2 dy}_{\langle G(\lambda)\eta_1, \eta_1 \rangle_{\mathcal{H}_S}}.$$

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$$\rightsquigarrow \lambda^2(\eta_1 + K(\lambda)\eta_1) + \lambda G(\lambda)\eta_1 + A_1\eta_1 = h.$$

A (tricky) perturbation argument allows to replace $G(\lambda)$ by $A_1^{1/4}$ and consider

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The non damped case $A_2 = 0$

From an integration by parts we first observe that

$$\langle L(\lambda)\eta_1, \eta_1 \rangle_{\mathcal{H}_S} = \lambda \underbrace{\int_{\mathcal{F}_{\eta_1^0}} |v_{\eta_1}|^2 dy}_{\langle K(\lambda)\eta_1, \eta_1 \rangle_{\mathcal{H}_S}} + \underbrace{\int_{\mathcal{F}_{\eta_1^0}} |\nabla v_{\eta_1}|^2 dy}_{\langle G(\lambda)\eta_1, \eta_1 \rangle_{\mathcal{H}_S}}.$$

$$\rightsquigarrow L(\lambda) = \lambda K(\lambda) + G(\lambda)$$

with $K(\lambda)$ and $G(\lambda)$ self-adjoint satisfying

$$0 < K(\lambda) \leq \rho_2 A_1^{-1/4} \quad \text{and} \quad \rho_1 A_1^{1/4} \leq G(\lambda) \leq \rho_2 \left(A_1^{1/4} + |\lambda| A_1^{-1/4} \right)$$

$$\rightsquigarrow \lambda^2(\eta_1 + K(\lambda)\eta_1) + \lambda G(\lambda)\eta_1 + A_1\eta_1 = h.$$

A (tricky) perturbation argument allows to replace $G(\lambda)$ by $A_1^{1/4}$ and consider

$$\lambda^2(\eta_1 + K(\lambda)\eta_1) + \lambda A_1^{1/4}\eta_1 + A_1\eta_1 = h.$$

The non damped case $A_2 = 0$

To simplify let consider the beam type resolvent equation :

$$\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1 = h.$$

We have the following result from the literature :

[Chen Triggiani, 1990]

Let $\alpha \in (0, 1/2)$. There exists $C > 0$ such that for all $\lambda \in \mathbb{C}^+$ the solution of

$$\lambda^2 \eta_1 + \lambda A_1^\alpha \eta_1 + A_1 \eta_1 = h,$$

satisfies

$$|\lambda|^{1+2\alpha} \|\eta_1\|_{\mathcal{H}_S} + |\lambda|^{-2\alpha} \|A_1 \eta_1\|_{\mathcal{H}_S} \leq C \|\lambda^2 \eta_1 + \lambda A_1^\alpha \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}.$$

As a consequence, the semigroup associated to the the underlying beam equation is of **Gevrey** class $\gamma > 1/2\alpha$.

With $\alpha = 1/4$ the semigroup is of **Gevrey** class $\gamma > 2$ and the estimate is

$$|\lambda|^{3/2} \|\eta_1\|_{\mathcal{H}_S} + |\lambda|^{-1/2} \|A_1 \eta_1\|_{\mathcal{H}_S} \leq C \|\lambda^2 \eta_1 + \lambda A_2 \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}.$$

The non damped case $A_2 = 0$

Proof of the simplified beam type resolvent estimate

$$|\lambda|^{3/2} \|\eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^{-1/2} \|A_1 \eta_1\|_{\mathcal{H}_S}^2 \leq C \|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}, (\lambda \in \mathbb{C}^+, |\lambda| > 1).$$

Step 1 :

$$\|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 \geq \|\lambda^2 \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^2 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2$$

Step 2 :

$$\|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 \geq |\lambda|^4 \|\eta_1\|_{\mathcal{H}_S}^2 + \|A_1 \eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^2 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2$$

The non damped case $A_2 = 0$

Proof of the simplified beam type resolvent estimate

$$|\lambda|^{3/2} \|\eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^{-1/2} \|A_1 \eta_1\|_{\mathcal{H}_S}^2 \leq C \|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}, (\lambda \in \mathbb{C}^+, |\lambda| > 1).$$

Step 1 :

$$\|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 \geq \|\lambda^2 \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^2 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2$$

Step 2 :

$$\|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 \geq |\lambda|^4 \|\eta_1\|_{\mathcal{H}_S}^2 + \|A_1 \eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^2 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2$$

The non damped case $A_2 = 0$

Proof of the simplified beam type resolvent estimate

$$|\lambda|^{3/2} \|\eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^{-1/2} \|A_1 \eta_1\|_{\mathcal{H}_S}^2 \leq C \|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}, (\lambda \in \mathbb{C}^+, |\lambda| > 1).$$

Step 1 :

$$\|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 \geq \|\lambda^2 \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^2 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2$$

Step 2 :

$$\begin{aligned} \|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 &\geq |\lambda|^4 \|\eta_1\|_{\mathcal{H}_S}^2 + \|A_1 \eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^2 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2 \\ &\quad + 2\operatorname{Re}(\lambda^2 \eta_1, A_1 \eta_1)_{\mathcal{H}_S} \end{aligned}$$

The non damped case $A_2 = 0$

Proof of the simplified beam type resolvent estimate

$$|\lambda|^{3/2} \|\eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^{-1/2} \|A_1 \eta_1\|_{\mathcal{H}_S}^2 \leq C \|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}, (\lambda \in \mathbb{C}^+, |\lambda| > 1).$$

Step 1 :

$$\|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 \geq \|\lambda^2 \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^2 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2$$

Step 2 :

$$\begin{aligned} \|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 &\geq |\lambda|^4 \|\eta_1\|_{\mathcal{H}_S}^2 + \|A_1 \eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^2 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2 \\ &\quad - 2(|\lambda|^{1/2} \|A_1^{3/4} \eta_1\|_{\mathcal{H}_S})(|\lambda|^{3/2} \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}) \end{aligned}$$

The non damped case $A_2 = 0$

Proof of the simplified beam type resolvent estimate

$$|\lambda|^{3/2} \|\eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^{-1/2} \|A_1 \eta_1\|_{\mathcal{H}_S}^2 \leq C \|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}, \quad (\lambda \in \mathbb{C}^+, |\lambda| > 1).$$

Step 1 :

$$\|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 \geq \|\lambda^2 \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^2 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2$$

Step 2 :

$$\begin{aligned} \|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 &\geq |\lambda|^4 \|\eta_1\|_{\mathcal{H}_S}^2 + \|A_1 \eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^2 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2 \\ &\quad - C(|\lambda|^4 \|\eta_1\|_{\mathcal{H}_S}^2 + \|A_1 \eta_1\|_{\mathcal{H}_S})^{1/2} (|\lambda|^3 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2)^{1/2} \end{aligned}$$

The non damped case $A_2 = 0$

Proof of the simplified beam type resolvent estimate

$$|\lambda|^{3/2} \|\eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^{-1/2} \|A_1 \eta_1\|_{\mathcal{H}_S}^2 \leq C \|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}, (\lambda \in \mathbb{C}^+, |\lambda| > 1).$$

Step 1 :

$$\|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 \geq \|\lambda^2 \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^2 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2$$

Step 2 :

$$\begin{aligned} & \|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 \\ & \geq \frac{1}{2} (|\lambda|^4 \|\eta_1\|_{\mathcal{H}_S}^2 + \|A_1 \eta_1\|_{\mathcal{H}_S}^2) + (|\lambda|^2 - c|\lambda|^3) \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2 \end{aligned}$$

The non damped case $A_2 = 0$

Proof of the simplified beam type resolvent estimate

$$|\lambda|^{3/2} \|\eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^{-1/2} \|A_1 \eta_1\|_{\mathcal{H}_S}^2 \leq C \|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}, (\lambda \in \mathbb{C}^+, |\lambda| > 1).$$

Step 1 :

$$\|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 \geq \|\lambda^2 \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^2 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2$$

Step 2 :

$$\|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 + c |\lambda|^3 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2 \geq \frac{1}{2} (|\lambda|^4 \|\eta_1\|_{\mathcal{H}_S}^2 + \|A_1 \eta_1\|_{\mathcal{H}_S}^2)$$

The non damped case $A_2 = 0$

Proof of the simplified beam type resolvent estimate

$$|\lambda|^{3/2} \|\eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^{-1/2} \|A_1 \eta_1\|_{\mathcal{H}_S}^2 \leq C \|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}, (\lambda \in \mathbb{C}^+, |\lambda| > 1).$$

Step 1 :

$$\|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 \geq \|\lambda^2 \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^2 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2$$

Step 2 :

$$\|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 + c|\lambda|^3 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2 \geq \frac{1}{2} (|\lambda|^4 \|\eta_1\|_{\mathcal{H}_S}^2 + \|A_1 \eta_1\|_{\mathcal{H}_S}^2)$$

Step 3 :

$$(1 + c|\lambda|) \|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 \geq \frac{1}{2} (|\lambda|^4 \|\eta_1\|_{\mathcal{H}_S}^2 + \|A_1 \eta_1\|_{\mathcal{H}_S}^2)$$

The non damped case $A_2 = 0$

Proof of the simplified beam type resolvent estimate

$$|\lambda|^{3/2} \|\eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^{-1/2} \|A_1 \eta_1\|_{\mathcal{H}_S}^2 \leq C \|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}, (\lambda \in \mathbb{C}^+, |\lambda| > 1).$$

Step 1 :

$$\|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 \geq \|\lambda^2 \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^2 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2$$

Step 2 :

$$\|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 + c |\lambda|^3 \|A_1^{1/4} \eta_1\|_{\mathcal{H}_S}^2 \geq \frac{1}{2} (|\lambda|^4 \|\eta_1\|_{\mathcal{H}_S}^2 + \|A_1 \eta_1\|_{\mathcal{H}_S}^2)$$

Step 3 :

$$C \|\lambda^2 \eta_1 + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|_{\mathcal{H}_S}^2 \geq (|\lambda|^3 \|\eta_1\|_{\mathcal{H}_S}^2 + |\lambda|^{-1} \|A_1 \eta_1\|_{\mathcal{H}_S}^2)$$

The non damped case $A_2 = 0$

A precise study of $K(\lambda)$ permits to adapt the previous proof and obtain :

$$|\lambda|^{3/2} \|\eta_1\|_{\mathcal{H}_S} + |\lambda|^{-1/2} \|A_1 \eta_1\|_{\mathcal{H}_S} \leq \|\lambda^2(\eta_1 + K(\lambda)\eta_1) + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|$$

$$K(\lambda)\eta = -\Lambda_{\eta_1^0}^* \mathbb{T}(\varphi_\eta, \pi_\eta) n \quad \left\{ \begin{array}{l} \bar{\lambda} \varphi_\eta - \operatorname{div} \mathbb{T}(\varphi_\eta, \pi_\eta) = v_\eta \quad \text{in } \mathcal{F}_{\eta_1^0}, \\ \operatorname{div} \varphi_\eta = 0 \quad \text{in } \mathcal{F}_{\eta_1^0}, \\ \varphi_\eta = 0 \quad \text{on } \partial \mathcal{F}_{\eta_1^0}, \\ \lambda v_\eta - \operatorname{div} \mathbb{T}(v_\eta, \rho_\eta) = 0 \quad \text{in } \mathcal{F}_{\eta_1^0}, \\ \operatorname{div} v_\eta = 0 \quad \text{in } \mathcal{F}_{\eta_1^0}, \\ v_\eta = \Lambda_{\eta_1^0} \eta \quad \text{on } \partial \mathcal{F}_{\eta_1^0}, \end{array} \right.$$

provides, in particular, the following key estimates :

$$\|A_1^{\theta/2} K(\lambda)\eta\|_{\mathcal{H}_S} \leq C \left(\|A_1^{\theta/2-1/4} \eta\|_{\mathcal{H}_S} + |\lambda|^{\theta-1/2+\varepsilon} \|\eta\|_{\mathcal{H}_S} \right) \quad (1/2 \leq \theta \leq 2).$$

$$\|[A_1^{3/8}, K(\lambda)]\eta\|_{\mathcal{H}_S} \leq C(|\lambda|^{-1} \|A_1^{1/2+\varepsilon} \eta\|_{\mathcal{H}_S} + |\lambda|^\varepsilon \|\eta\|_{\mathcal{H}_S})$$

The non damped case $A_2 = 0$

A precise study of $K(\lambda)$ permits to adapt the previous proof and obtain :

$$|\lambda|^{3/2} \|\eta_1\|_{\mathcal{H}_S} + |\lambda|^{-1/2} \|A_1 \eta_1\|_{\mathcal{H}_S} \leq \|\lambda^2(\eta_1 + K(\lambda)\eta_1) + \lambda A_1^{1/4} \eta_1 + A_1 \eta_1\|$$

$$K(\lambda)\eta = -\Lambda_{\eta_1^0}^* \mathbb{T}(\varphi_\eta, \pi_\eta) n \quad \left\{ \begin{array}{ll} \bar{\lambda} \varphi_\eta - \operatorname{div} \mathbb{T}(\varphi_\eta, \pi_\eta) = \mathbf{v}_\eta & \text{in } \mathcal{F}_{\eta_1^0}, \\ \operatorname{div} \varphi_\eta = 0 & \text{in } \mathcal{F}_{\eta_1^0}, \\ \varphi_\eta = 0 & \text{on } \partial \mathcal{F}_{\eta_1^0}, \\ \lambda \mathbf{v}_\eta - \operatorname{div} \mathbb{T}(\mathbf{v}_\eta, \mathbf{p}_\eta) = 0 & \text{in } \mathcal{F}_{\eta_1^0}, \\ \operatorname{div} \mathbf{v}_\eta = 0 & \text{in } \mathcal{F}_{\eta_1^0}, \\ \mathbf{v}_\eta = \Lambda_{\eta_1^0} \eta & \text{on } \partial \mathcal{F}_{\eta_1^0}, \end{array} \right.$$

provides, in particular, the following key estimates :

$$\|A_1^{\theta/2} K(\lambda)\eta\|_{\mathcal{H}_S} \leq C \left(\|A_1^{\theta/2-1/4} \eta\|_{\mathcal{H}_S} + |\lambda|^{\theta-1/2+\varepsilon} \|\eta\|_{\mathcal{H}_S} \right) \quad (1/2 \leq \theta \leq 2).$$

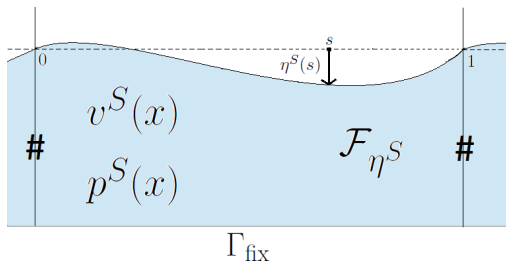
$$\|[A_1^{3/8}, K(\lambda)]\eta\|_{\mathcal{H}_S} \leq C(|\lambda|^{-1} \|A_1^{1/2+\varepsilon} \eta\|_{\mathcal{H}_S} + |\lambda|^\varepsilon \|\eta\|_{\mathcal{H}_S})$$

$$\rightsquigarrow \eta_1^0 \in W^{7,\infty}(0,1)$$

Outline

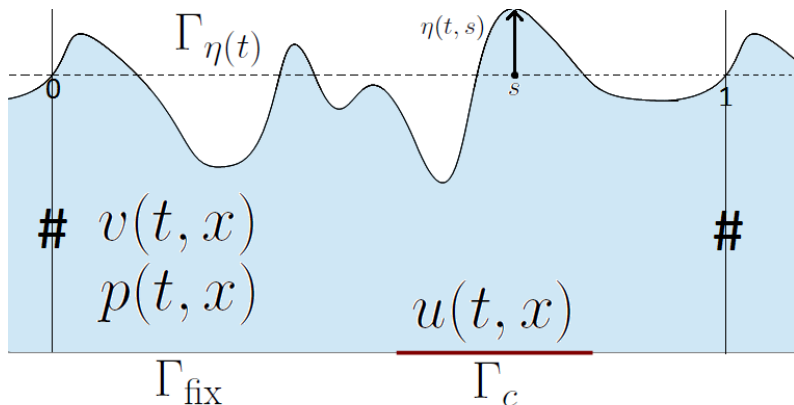
- 1 Presentation of the problem
- 2 Sketch of the proof
- 3 A control issue**

Target state



$$\left\{ \begin{array}{l} (v^S \cdot \nabla)v^S - \operatorname{div} \mathbb{T}(v^S, p^S) = f^S \quad \text{in } \mathcal{F}_{\eta^S}, \\ \operatorname{div} v^S = 0 \quad \text{in } \mathcal{F}_{\eta^S} \\ v^S = 0 \quad \text{on } \Gamma_{\eta^S}, \\ v^S = b^S \quad \text{on } \Gamma_{\text{fix}}, \\ A_1 \eta^S = -\Lambda_{\eta^S}^* \mathbb{T}(v^S, p^S)n + Mg^S. \end{array} \right.$$

Control problem



Find a control u such that $\lim_{t \rightarrow +\infty} (v(t), \eta(t)) = (v^S, \eta^S)$,

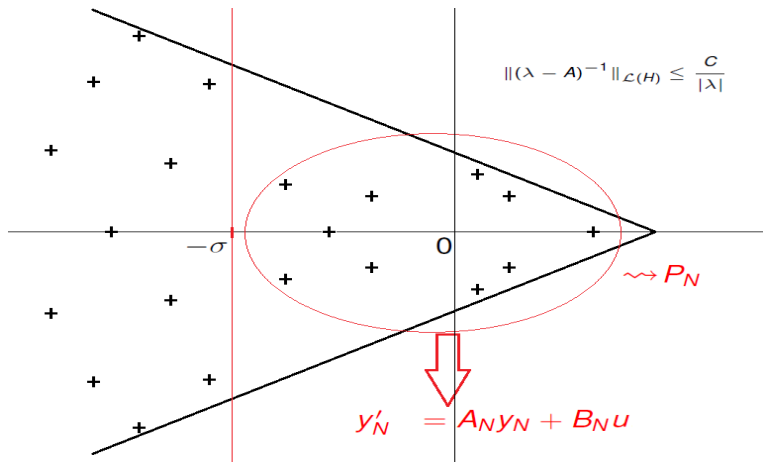
Control system

$$\left\{ \begin{array}{l} \partial_t \mathbf{v} + (\mathbf{v} \cdot \nabla) \mathbf{v} - \operatorname{div} \mathbb{T}(\mathbf{v}, \mathbf{p}) = \mathbf{f}^S \quad \text{in } \mathcal{F}_{\eta(t)}, \quad t > 0 \\ \operatorname{div} \mathbf{v} = 0 \quad \text{in } \mathcal{F}_{\eta(t)}, \quad t > 0 \\ \mathbf{v} = (\partial_t \eta) \vec{\mathbf{e}}_2 \quad \text{on } \Gamma_{\eta(t)}, \quad t > 0 \\ \mathbf{v} = \mathbf{b}^S + \mathbf{u} \quad \text{on } \Gamma_{\text{fix}}, \quad t > 0 \\ \partial_{tt} \eta + \mathbf{A}_2 \partial_t \eta + \mathbf{A}_1 \eta = -\Lambda_{\eta}^* \mathbb{T}(\mathbf{v}, \mathbf{p}) \mathbf{n} + M \mathbf{g}^S, \quad t > 0, \\ \eta(0) = \eta_1^0, \quad \partial_t \eta(0) = \eta_2^0, \quad \mathbf{v}(0, \mathbf{x}) = \mathbf{v}^0(\mathbf{x}) \quad \mathbf{x} \in \mathcal{F}_{\eta_1^0}. \end{array} \right.$$

Control system obtained by linearizing around $(\mathbf{v}^S, 0, \eta^S)$:

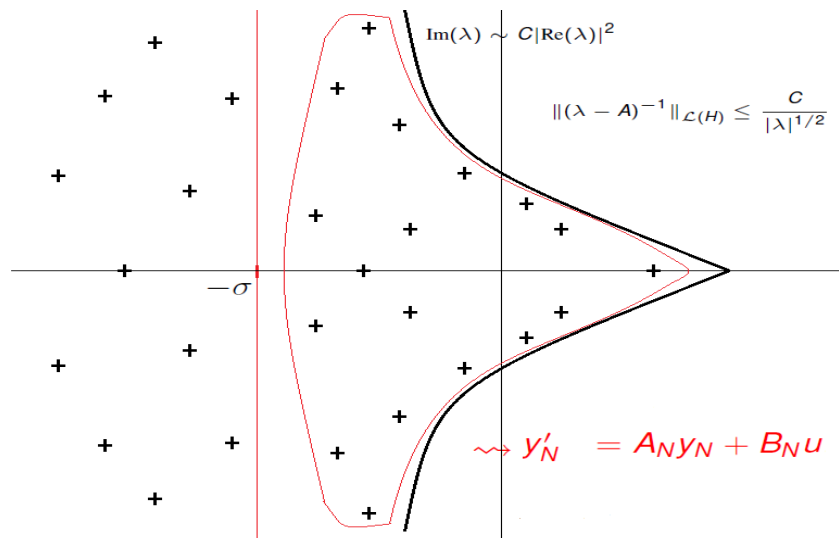
$$\rightsquigarrow Y' = AY + Bu, \quad Y(0) = Y_0 \in H$$

Projected system (damped case $A_2 = -\delta \partial_{SS}$, $\delta > 0$)



\rightsquigarrow B-Takahashi (2017) : Stabilization by finite dimensional feedback control.

Projected system (non damped case $A_2 = 0$)



~> work in progress !!!

Thank you for your attention !