

Controllability of the Wave Equation with Rough Coefficients

Part I ¹

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$$(W) \quad \begin{cases} \partial_t^2 u - \Delta_x u = 0 & \text{in }]0, +\infty[\times M \\ (u(0), \partial_t u(0)) = (u_0, u_1) \in H^1 \times L^2 \end{cases}$$

- M Riemannian manifold, connected, compact, without boundary, with dimension d .
- $M = \Omega$ open subset of \mathbb{R}^d , connected, bounded, with "smooth" boundary (homogeneous Dirichlet condition).

$$H = C([0, +\infty[, H^1) \cap C^1([0, +\infty[, L^2)$$

→ Consider ω an open subset of M and Γ an open subset of $\partial\Omega$ and also a time $T > 0$.

The Goal

Provide internal or boundary exact control results in the case of **non smooth metrics**.

Given (u_0, u_1) , find a control vector f (resp. g) s.t the solution of

$$\begin{cases} \partial_t^2 u - \Delta_x u = \chi_\omega f \\ (u(0), \partial_t u(0)) = (u_0, u_1) \end{cases}$$

resp.

$$\begin{cases} \partial_t^2 u - \Delta_x u = 0 \\ u = \chi_\Gamma g \quad \text{on } \partial\Omega \\ (u(0), \partial_t u(0)) = (u_0, u_1) \end{cases}$$

satisfies $u(T) = \partial_t u(T) = 0$.

Tool : By HUM , we need an **observability estimate** for the wave equation (W).

Boundary observation

$$Eu(0) \leq c \int_0^T \int_{\Gamma} \left| \frac{\partial u}{\partial n}(t, x) \right|^2 d\sigma dt$$

Remark: The converse is "always" true :

$$\int_0^T \int_{\partial\Omega} \left| \frac{\partial u}{\partial n}(t, x) \right|^2 d\sigma dt \leq c Eu(0)$$

→ Hidden regularity.

Internal observation

$$Eu(0) \leq c \int_0^T \int_{\omega} |\partial_t u(t, x)|^2 dx dt \quad (O)$$

Or at least

$$Eu(0) \leq c \int_0^T \int_{\omega} |\partial_t u(t, x)|^2 dx dt + c \|(u_0, u_1)\|_{L^2(M) \times H^{-1}(M)}^2 \quad (RO)$$

→ unique continuation property....

Or either observation with loss

$$Eu(0) \leq c \|u\|_{H^m((0, T) \times \omega)}^2, \quad m > 1 \quad (OL)$$

Remark : If M is a compact manifold without boundary, we consider instead the Klein-Gordon equation

$$\partial_t^2 u - \Delta_x u + u = 0$$

→ **Exact controllability** (HUM)

→ **Stabilization**

$$Eu(t) \leq C \exp^{-\gamma t} Eu(0)$$

for solutions of the damped equation

$$\partial_t^2 u - \Delta_x u + a(x) \partial_t u = 0$$

→ **Inverse problems**

Stability results,

State of the art

- 80' : Observability estimates under the Γ -condition of J.L. Lions.
 - Metric of class C^1 .
 - Multiplier techniques.
- 90' : Microlocal conditions and microlocal tools (Rauch and Taylor, Bardos, Lebeau and Rauch, Burq and Gérard).
The geometric control condition (**G.C.C**) : a microlocal condition, stated in the cotangent bundle (of Melrose-Sjostrand).
 - Microlocal and pseudo-differential techniques : propagation of wave front sets and supports of microlocal defect measures.
 - The condition is optimal but..... a priori needs smooth metric and smooth boundary.
- 97' N. Burq : Boundary observability: C^2 -metric and C^3 -boundary.

Geometric Control Condition I

The couple (ω, T) satisfies the geometric control condition (G.C.C), if every geodesic of Ω issued at $t = 0$ and travelling with speed 1, enters in ω before the time T .

Geometric Control Condition II

The couple (Γ, T) satisfies the geometric control condition (G.C.C), if every generalized bicharacteristic of the wave symbol, issued at $t = 0$, intersects the boundary subset Γ at a nondiffractive point, before the time T .

Some Functional Spaces

$a(x)$ is resp. Zygmund or Log-Zygmund continuous function if

$$|h| < 1,$$

$$\begin{cases} |a(x+h) + a(x-h) - 2a(x)| \leq K|h| \\ |a(x+h) + a(x-h) - 2a(x)| \leq K|h|(1 - \text{Log}|h|) \end{cases}$$

For $0 < \alpha < 1$,

$$W^{1,\infty} = \text{Lip} \subset Z = C_*^1 \subset LL \subset LZ \subset C^\alpha$$

The OL theorem of Fanelli-Zuazua (2014)

1-D setting, $\Omega =]0, 1[$, $a(x)\partial_t^2 u - \partial_x^2 u = 0$.

Theorem (Fanelli - Zuazua 1)

Assume $a(x) \in Z$, then for $T > T_a$, there exists $C > 0$ s.t

$$Eu(0) \leq C \int_0^T |\partial_x u(t, 0)|^2 dt \quad (1)$$

Theorem (Fanelli - Zuazua 2)

Assume $a(x) \in LZ$ and denote $D_a f = a(x)^{-1} \partial_x^2 f$. Then for $T > T_a$, there exist $C > 0$ and $m \in \mathbb{N}$ s.t

$$Eu(0) \leq C \int_0^T |\partial_t^m \partial_x u(t, 0)|^2 dt \quad (2)$$

for all initial data $(u_0, u_1) \in (H^{2m+1} \cap H_0^1) \times H^{2m}$ satisfying
 $D_a^m u_0 \in H^1$ $D_a^m u_1 \in L^2$

Comments

- Classical boundary observation in Th. 1 and boundary observation with **loss** in Th. 2.
- For $a(x)$ worse than LZ , infinite loss of derivatives :
No Observability !
See also the counter-example of Castro - Zuazua ('03').
- Proof: 1-dimensional technique: the sidewise energy estimates, i.e hyperbolic energy estimates by interchanging time \longleftrightarrow space.
(Colombini, Spagnolo, Lerner, Métivier, Fanelli....)
- 1-D geometry: all characteristic rays reach the boundary in uniform time.

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- 1-D geometry: all characteristic rays reach the boundary in uniform time.
- **Question:** What about dimensions higher than 1, where geometry is more evolved ???

Case of a continuous density $a(x)$ in \mathbb{R}^d

$$(W) \quad \begin{cases} a(x)\partial_t^2 u - \Delta_x u = 0 & \text{in } (0, T) \times \Omega, \\ u = 0 & \text{on } (0, T) \times \partial\Omega, \\ (u(0), \partial_t u(0)) \in H_0^1 \times L^2 \end{cases}$$

Assumption : There exists $\alpha \in (0, 2]$, s.t

$$x \cdot \nabla a(x) + (2 - \alpha)a(x) \geq 0 \quad \text{in the sense of } \mathcal{D}'(\mathbb{R}^d).$$

$$\forall \varphi \in D(\mathbb{R}^d), \text{ with } \varphi \geq 0, \quad \int_{\mathbb{R}^d} a(x) (-\operatorname{div}(x\varphi(x)) + (2 - \alpha)\varphi(x)) \, dx \geq 0$$

Observation region

ω an open neighborhood (in Ω) of an open subset Γ of the boundary satisfying the multiplier condition, i.e

$$\{x \in \partial\Omega, \text{ such that } x \cdot n_x > 0\} \subset \Gamma,$$

Let $R = \sup\{|x|, x \in \Omega\}$ and $a_1 = \sup\{a(x), x \in \bar{\Omega}\}$

Theorem (D-Ervedoza 17')

For $\alpha T > 4R\sqrt{a_1}$, there exists a constant $C > 0$ s.t the observability estimate

$$Eu(0) \leq C \int_0^T \int_{\omega} |\partial_t u(t, x)|^2 dx dt$$

holds true for every solution of (W).

Examples

- One can take $a(x) = a(r, \theta) = f(r)g(\theta)$ with f, g positive continuous, and $f'(r) \geq 0$ in the sense of distributions.

→ Allows highly oscillating function $g(\theta)$.

- $\Omega = B(0, R) \setminus B(0, R_1)$, $0 < R_1 < R$, and $a(x) = 1/r^2$.

Take $x_0 \in \Omega$, $\xi_0 \neq 0$, $x_0 \cdot \xi_0 = 0$, and $\tau_0 = |x_0||\xi_0|$

The ray $\gamma(s)$ issued from $(0, x_0, \tau_0, \xi_0)$ satisfies

$$\frac{d^2}{ds^2} (|x(s)|^2) = 0 \quad \text{and} \quad \frac{d}{ds} (|x(s)|^2) \Big|_{s=0} = 0$$

→ $|x(s)| = |x_0|$ Captive ray !

Stability properties

Denote $A(x) = (a_{ij}(x))$, $d \times d$ symmetric definite positive matrix, and κ a real valued function, $\kappa(x) > 0$ (a density).

Denote $\mathcal{A} = (A, \kappa)$,

$$\Delta_{\mathcal{A}} = \frac{1}{\kappa(x)} \sum_{ij} \partial_j a_{ij}(x) \kappa(x) \partial_i$$

and consider the wave operator

$$P_{\mathcal{A}} = \partial_t^2 - \Delta_{\mathcal{A}}$$

Theorem (Burq-D-Le Rousseau 19')

Assume that $\mathcal{A} = (A, \kappa)$ is smooth and that (ω, T) (resp. (Γ, T)) satisfies (GCC) for $P_{\mathcal{A}}$.

Take $\mathcal{B} \in \mathcal{U}_{\varepsilon}$, an ε -neighborhood of \mathcal{A} in $W^{1,\infty}$.

Then for ε **small enough**, the (classical) observability estimate holds true

$$Eu(0) \leq c \int_0^T \int_{\omega} |\partial_t u(t, x)|^2 \kappa dx dt \quad \left(\text{resp. } \int_0^T \int_{\Gamma} \left| \frac{\partial u}{\partial n}(t, x) \right|^2 \kappa d\sigma dt \right)$$

for every solution of

$$P_{\mathcal{B}}u = \partial_t^2 u - \Delta_{\mathcal{B}}u = 0, \quad u|_{\partial\Omega} = 0$$

Corollary

Under conditions above, we get exact controllability for $P_{\mathcal{B}} = \partial_t^2 - \Delta_{\mathcal{B}}$, in time T .

Comments

- No geometry setting for the metric B !!!
- One can replace $Eu(0)$ by $E_B u(0)$.
- One can also consider the same problem on a perturbed domain Ω_ε , with $W^{2,\infty}$ perturbation.

metric $A \longrightarrow B = A_\varepsilon \quad W^{1,\infty} \quad \varepsilon - \text{perturbation}$

domain $\Omega \longrightarrow \Omega_\varepsilon \quad W^{2,\infty} \quad \varepsilon - \text{perturbation}$

→ For a given metric $B \in W^{1,\infty}$, we cannot decide if P_B is observable or not.

In particular, what happens for $B \in C^1$ and $\partial\Omega$ of class C^2 ???

Next lecture by Jérôme !

$$(W) \quad \begin{cases} \partial_t^2 u - \Delta_{\mathcal{A}} u = \chi_{\omega}^2(x)f & \text{in }]0, T[\times \Omega \\ u = 0 & \text{on }]0, T[\times \partial\Omega \\ (u(0), \partial_t u(0)) = (u_0, u_1) \in H_0^1 \times L^2 \end{cases}$$

We look for $f \in L^2(]0, T[\times \Omega)$, s.t

$$(u(T), \partial_t u(T)) = (0, 0)$$

By HUM and **under (G.C.C)**, we can take f solution of

$$(W') \quad \begin{cases} \partial_t^2 f - \Delta_{\mathcal{A}} f = 0 & \text{in }]0, T[\times \Omega \\ f = 0 & \text{on }]0, T[\times \partial\Omega \\ (f(0), \partial_t f(0)) = (f_0, f_1) \in L^2 \times H^{-1} \end{cases}$$

The map

$$\left\{ \begin{array}{l} \Lambda : H_0^1 \times L^2 \rightarrow L^2 \times H^{-1} \\ (u_0, u_1) \rightarrow (f_0, f_1) \end{array} \right.$$

is an isomorphism; this is **HUM optimal control operator**.

Denote by $f_{\mathcal{A}}$ the HUM control attached to $P_{\mathcal{A}}$, i.e the solution of (W') .

Theorem (D-Lebeau, 2009)

In the setting above and under (G.C.C),

a) *For all $s \geq 0$,*

$$\Lambda : H^{s+1} \times H^s \rightarrow H^s \times H^{s-1}$$

is an isomorphism.

b)

$$\left\| \Lambda \psi(2^{-k}D) - \psi(2^{-k}D)\Lambda \right\| \leq C2^{-k/2}$$

c) *If M is a Riemannian manifold without boundary, Λ is a pseudo differential operator.*

Behavior of the HUM control process

Let $\mathcal{A} = (A, \kappa)$ be smooth (C^2) and such that (ω, T) satisfies (GCC).

Theorem (Burq-D-Le Rousseau 19')

For any C^2 - neighborhood \mathcal{U} of \mathcal{A} , there exist $\mathcal{A}' \in \mathcal{U}$ and an initial data (u_0, u_1) , $\|(\nabla_A u_0, u_1)\|_{L^2 \times L^2} = 1$, s.t the respective solutions u and v of

$$\left\{ \begin{array}{l} \partial_t^2 u - \Delta_{\mathcal{A}} u = \chi_\omega^2(x) f_{\mathcal{A}} \\ \partial_t^2 v - \Delta_{\mathcal{A}'} v = \chi_\omega^2(x) f_{\mathcal{A}} \\ (u(0), \partial_t u(0)) = (v(0), \partial_t v(0)) = (u_0, u_1) \in H_0^1 \times L^2 \end{array} \right.$$

satisfy

$$E_{\mathcal{A}}(u - v)(T) = E_{\mathcal{A}}(v)(T) \geq 1/2$$

Moreover,

$$\|f_{\mathcal{A}} - f_{\mathcal{A}'}\|_{L^2((0, T) \times \omega)} \geq 1/\sqrt{8T}$$

Remarks

- (GCC) also satisfied by (ω, T) for the metric \mathcal{A}' .
→ $f_{\mathcal{A}'}$ is well defined.
- For fixed initial data, the map

$$(\mathcal{C}^2(\Omega))^{d^2+1} \longrightarrow L^2((0, T) \times \omega)$$

$$\mathcal{A} = (A, \kappa) \longrightarrow f_{\mathcal{A}}$$

is not continuous.

Proof

→ Choose $A' = (1 + \varepsilon)A$

→ Take a sequence (u_0^k, u_1^k) such that $\|(\nabla u_0^k, u_1^k)\|_{L^2 \times L^2} = 1$ and $(u_0^k, u_1^k) \rightarrow (0, 0)$ in $H_0^1 \times L^2$.

→ $f_{\mathcal{A}}^k \rightarrow 0$ in $L^2((0, T) \times \Omega)$. Hence $f_{\mathcal{A}}^k \rightarrow 0$ in $H^{-1}((0, T) \times \Omega)$ and $\text{supp}\mu(f_{\mathcal{A}}^k) \subset \text{Char}(\partial_t^2 - \Delta_{\mathcal{A}}) = \{\tau^2 - A_x(\xi, \xi) = 0\}$.

→ $\text{supp}\mu(v^k) \subset \text{Char}(\partial_t^2 - \Delta_{\mathcal{A}'}) = \{\tau^2 - A'_x(\xi, \xi) = 0\}$

→ $\text{supp}\mu(v^k) \cap \text{supp}\mu(f_{\mathcal{A}}^k) = \emptyset$

$$E_{\mathcal{A}'}(v^k)(T) - E_{\mathcal{A}'}(v^k)(0) = 2 \int_0^T \int_{\Omega} \chi_{\omega}^2(x) f_{\mathcal{A}}^k \partial_t v^k \, dx dt \rightarrow 0.$$

On the other hand, decompose this function v as $v = v_1 + v_2$ where

$$\begin{cases} \square_{A'} v_1 = \chi_\omega^2(x) f_{A'} & (v_1(0), \partial_t v_1(0)) = (u_0, u_1) \\ \square_{A'} v_2 = \chi_\omega^2(x) (f_A - f_{A'}) & (v_2(0), \partial_t v_2(0)) = (0, 0) \end{cases}$$

Clearly $(v_1(T), \partial_t v_1(T)) = (0, 0)$, hence $E_{A'}(v)(T) = E_{A'}(v_2)(T)$

→ Conclude with hyperbolic energy estimate.

Theorem (Control of smooth data)

Assume that (ω, T) satisfies (GCC) for the metric A . Then for any metric B of class C^1 , and any $\alpha \in]0, 1]$, the respective solutions u and v of

$$\left\{ \begin{array}{ll} P_A u = \chi_\omega^2(x) f_A & \text{in } (0, T) \times \Omega \\ P_B v = \chi_\omega^2(x) f_A & \text{in } (0, T) \times \Omega \\ u = v = 0 & \text{on } (0, T) \times \partial\Omega \\ (u(0), \partial_t u(0)) = (v(0), \partial_t v(0)) = (u_0, u_1) \in H^{1+\alpha}(\Omega) \times H^\alpha(\Omega) \end{array} \right.$$

satisfy

$$E_A^{1/2}(u - v)(T) \leq c_\alpha \|A - B\|_{C^1}^\alpha \times \|(u_0, u_1)\|_{H^{1+\alpha} \times H^\alpha}$$

for some constant $c_\alpha > 0$.

Strategy

→ First prove

$$Eu(0) \leq c \int_0^T \int_{\omega} |\partial_t u(t, x)|^2 dx dt + \|(u_0, u_1)\|_{L^2 \times H^{-1}}^2$$

→ In the smooth case :

Contradiction argument and propagation of micro local defect measures.

→ Contradiction argument

$$\left\{ \begin{array}{l} Eu^k(0) = 1, \quad (u^k) \text{ solution of (W)}, \\ \int_0^T \int_\omega |\partial_t u^k(t, x)|^2 dx dt + \|(u_0^k, u_1^k)\|_{L^2(M) \times H^{-1}(M)}^2 \leq 1/k \end{array} \right.$$

$$\left\{ \begin{array}{l} u^k \rightarrow 0 \quad \text{in} \quad H^1((0, T) \times M), \\ \int_0^T \int_\omega |\partial_t u^k(t, x)|^2 dx dt \rightarrow 0 \end{array} \right.$$

Let μ be a **microlocal defect measure** attached to u_k .

→ $\mu = 0$ over $(0, T) \times \omega$ and by **propagation** and GCC, $\mu = 0$ everywhere.

Contradiction with $Eu^k(0) = 1$.

Back to non smooth metric

To be achieved : Prove a propagation result for μ , in a low regularity setting.

Stability result : Boundaryless case (Warm up)

Contradiction argument

Recall : $A(x) = (a_{ij}(x))$, $d \times d$ symmetric definite positive matrix, and κ a real valued function, $\kappa(x) > 0$ (a density).

Denote $\mathcal{A} = (A, \kappa)$,

$$\Delta_{\mathcal{A}} = \frac{1}{\kappa(x)} \sum_{ij} \partial_j a_{ij}(x) \kappa(x) \partial_i$$

and consider the **Klein-Gordon** equation :

$$Pu = \partial_t^2 u - \Delta_{\mathcal{A}} u + u = 0 \quad \text{on } (0, T) \times \Omega$$

→ Consider a sequence of $\mathcal{A}_k = (A_k, \kappa_k)$ s.t

$$\|\mathcal{A} - \mathcal{A}_k\|_{W^{1,\infty}} \rightarrow 0, \quad \text{and for each } k, \quad \|(u_0^{k,p}, u_1^{k,p})\|_{H^1 \times L^2} = 1$$

$$\begin{cases} P_k u_k^p = \partial_t^2 u_k^p - \Delta_{\mathcal{A}_k} u_k^p + u_k^p = 0 & \text{on } (0, T) \times \Omega \\ u_k^p(0) = u_0^{k,p}, \quad \partial_t u_k^p(0) = u_1^{k,p} \end{cases}$$

and

$$\int_0^T \int_{\omega} |\partial_t u_k^p|^2 dx dt \leq 1/p.$$

Denote $u_k^k \rightsquigarrow u_k$,

$$\left\{ \begin{array}{l} P_k u_k = \partial_t^2 u_k - \Delta_{\mathcal{A}_k} u_k + u_k = 0 \quad \text{on } (0, T) \times \Omega \\ \|(u_0^k, u_1^k)\|_{H^1 \times L^2} = 1 \\ \int_0^T \int_{\omega} |\partial_t u_k|^2 dx dt \rightarrow 0 \end{array} \right.$$

and assume

$$u_k \rightharpoonup 0 \quad \text{weakly in } H^1((0, T) \times \Omega)$$

Let μ be a microlocal defect measure attached to the sequence u_k .

$$P_0 u_k = (P_0 - P_k) u_k = (\Delta_{\mathcal{A}_k} - \Delta_{\mathcal{A}}) u_k \longrightarrow 0 \quad \text{in } H^{-1}$$

Consider $Q = q(t, x; D_t, D_x) \in Op(S_{cl}^1)$.

And calculate the bracket

$$\left([P_0, Q] u_k, u_k \right)_{L^2} = \left([\Delta_{\mathcal{A}_k} - \Delta_{\mathcal{A}}, Q] u_k, u_k \right)_{L^2} + o(1/k)$$

Theorem (Calderon, Coifman-Meyer 85')

For any function $m \in W^{1,\infty}(\mathbb{R}^{d+1})$, the bracket $[m, Q]$ continuously maps $L^2(\mathbb{R}^{d+1})$ in itself and

$$\| [m, Q] \|_{L^2 \rightarrow L^2} \leq C \| m \|_{W^{1,\infty}}$$

Thus $\left([P_0, Q] u_k, u_k \right)_{L^2} \longrightarrow 0$ and ${}^t H_{p_0} \mu = 0$.

μ is invariant along the hamiltonian flow of P_0 (propagation).

If we look carefully, the previous bracket calculus also works for a referential metric of class C^1 .

This gives

$${}^t H_{p_0} \mu = 0$$

where the vector field H_{p_0} has continuous coefficients.

→ How to deal with this measure equation ?

Next lecture by Jérôme !